

Applications of multiple DBMSs and algorithms for time-domain astronomy

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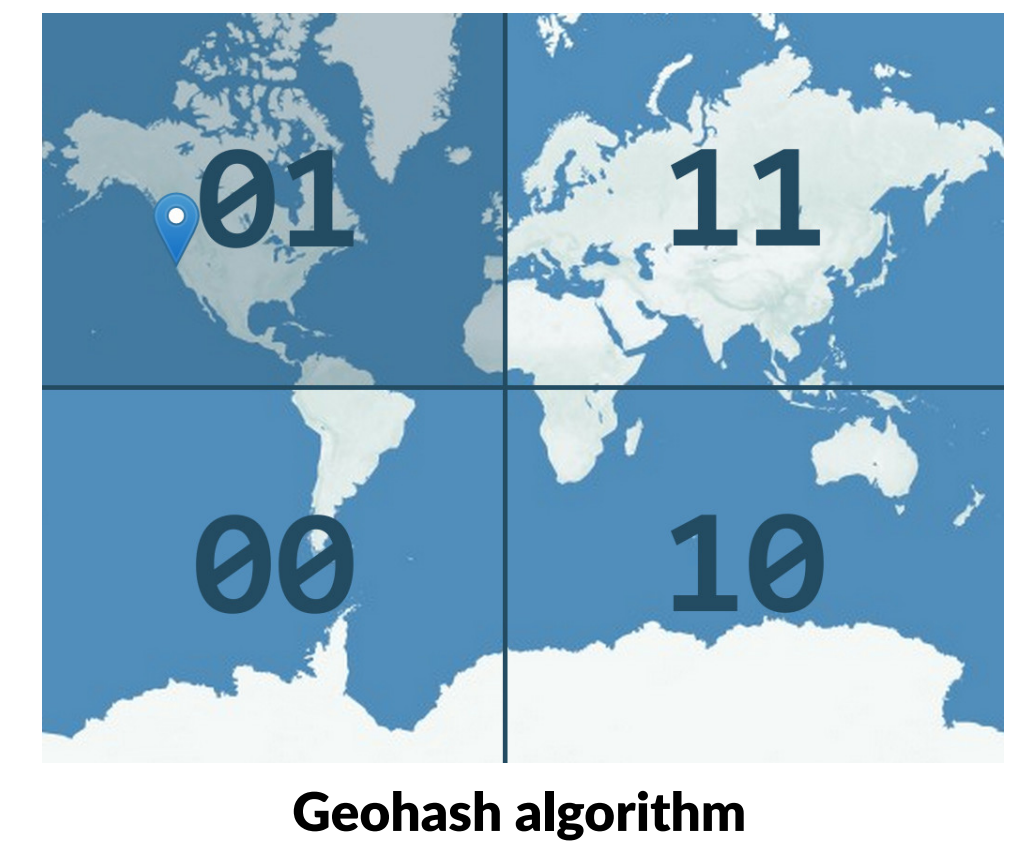
We use multiple DBMSs and algorithms in the follow-up target selection step, processing follow-up observation data, and cataloging reduced data and light curves. The current system is used in our pilot program of time-domain follow-up observations.

1. Redis: GeoSet (a sorted set with latitude and longitude)

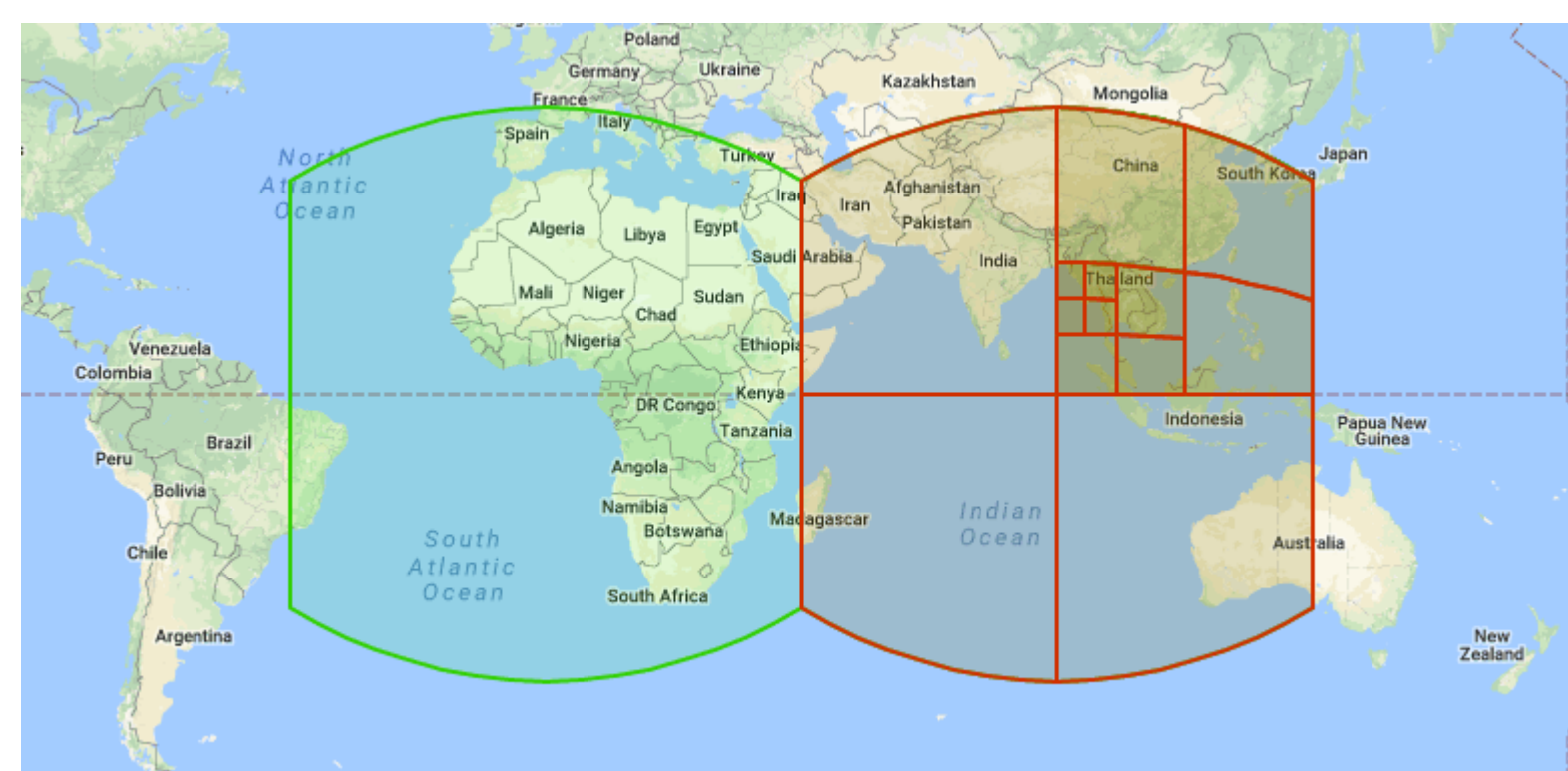
Low-latency in-memory spatial data store for astronomical coordinates.

– Modified version of the Redis to store custom catalogs with coordinates for follow-up target selection or local catalog search purposes.

– Typical search response time ~ microseconds to milliseconds thanks to the geohash algorithm.



Geohash algorithm



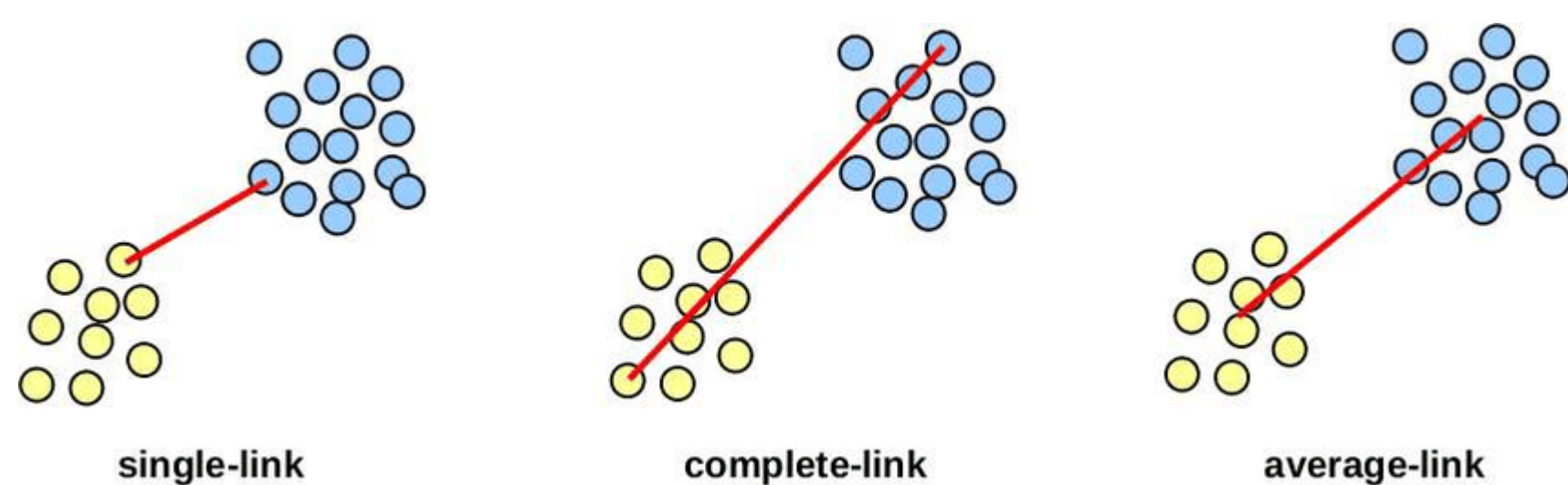
2. Google's S2 Geometry library

Constructing light curves and physical object catalogs by single-linkage (i.e., friends-of-friends) clustering of detected sources with helps of **Google's S2 Geometry library for fast spatial search.**

– Input: catalogs of detected sources with their positions in optical observations for given observation fields.

– Output: light curves and physical objects defined as grouped sources with a given linking angular distance in the single-linkage single-level clustering.

– Our program written in C++ using Google's S2 Geometry library for indexing detected sources and searching the nearest neighbor in the single-linkage clustering.



3. ClickHouse: column-oriented DBMS for source and object catalogs

Our requirements for data store of source, object, and image catalogs:

– Horizontally scalable (i.e. sharding) with commodity hardware.

– SQL-like query support.

– Reasonable data ingestion performance.

– Fast search query performance with group by observation field names or for spatiotemporal constraints.



Our consideration and test of three open-source systems: **ClickHouse, RethinkDB, and Vitess.**

– Vitess: (pros) the most powerful choice with the broad supports of MySQL features and sharding with various custom rules, (cons) requirements of the k8s cluster and large resources.

– RethinkDB: (pros) automatic sharding and fast response in ingestion and search, (cons) weak community development and large resources.

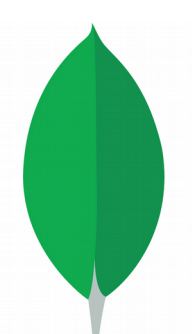
– ClickHouse: (pros) the efficient usage of resources, supports of sharding with SQL-like languages, (cons) the limited support of sharding rules and no geodata features. → We adopt the **ClickHouse as the main store of source, object, and image catalogs for their fixed schema and infrequent usage of entire columns.**

4. MongoDB: document-oriented DBMS for light curves

– Why?

a. different sizes and contents of light curves well matched to documents stored in MongoDB.

b. supports of sharding and geodata in document-format data.



mongoDB

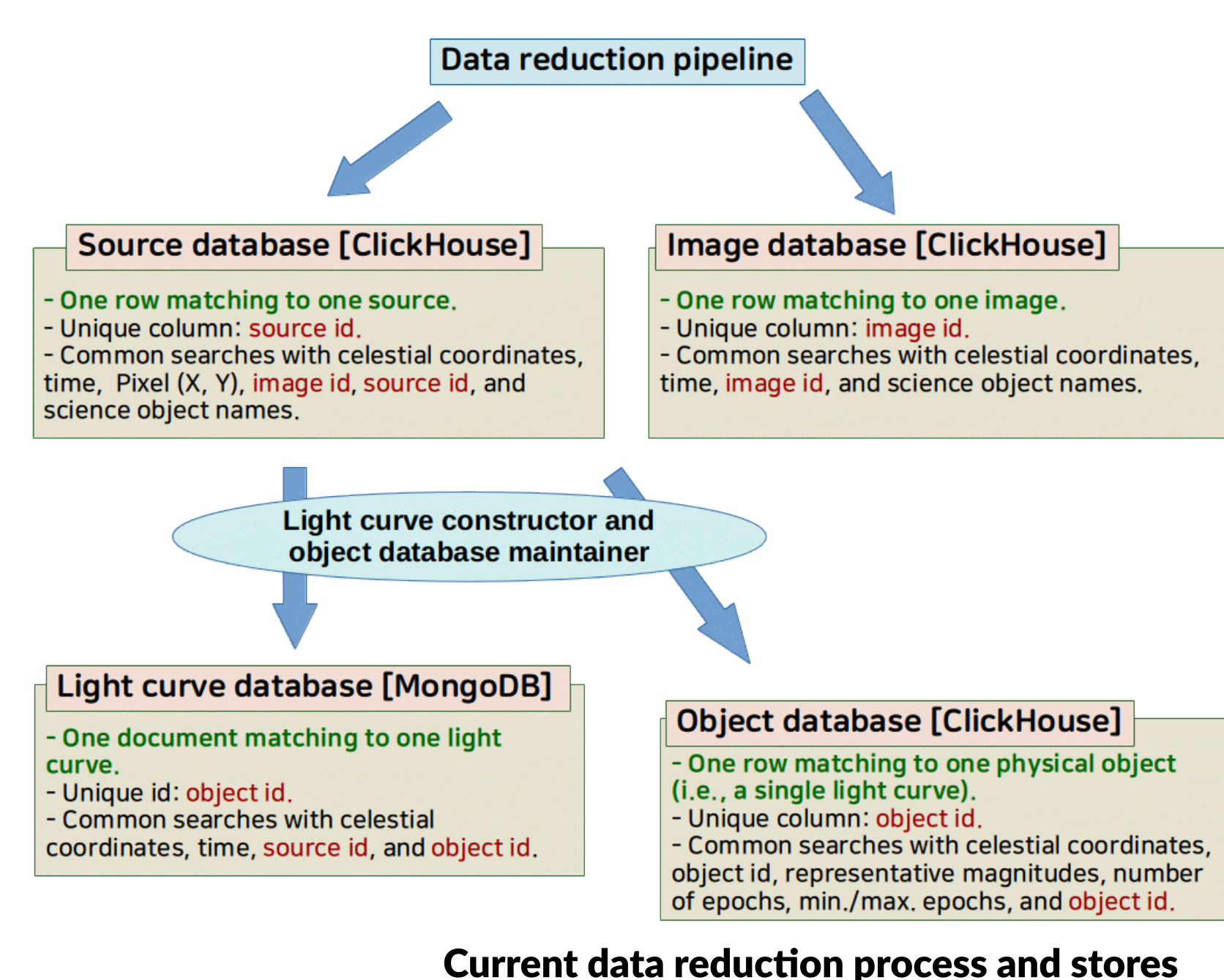
```
source_id CHAR(40) NOT NULL,
seq INT UNSIGNED NOT NULL,
# source sequence number (for a specific amp)
filter CHAR(1),
image_id CHAR(40) NOT NULL,
sci_obj_name CHAR(128),
mjd DOUBLE NOT NULL,
# MJD (day)
x DOUBLE NOT NULL,
# X image (SEXTRACTOR KEYWORDS)
y DOUBLE NOT NULL,
# Y image (SEXTRACTOR KEYWORDS)
ra_deg DOUBLE NOT NULL,
# RA world (SEXTRACTOR KEYWORDS; degree)
dec_deg DOUBLE NOT NULL,
# DEC world (SEXTRACTOR KEYWORDS; degree)
ra_dec_point POINT NOT NULL SRID 4326,
mag_auto DOUBLE,
# calibrated Mag. auto (SEXTRACTOR KEYWORDS; mag_auto)
magerr_auto DOUBLE,
# uncertainty of mag_auto (SEXTRACTOR KEYWORDS; mag_auto uncertainty)
bkg DOUBLE,
# background at centroid position (SEXTRACTOR KEYWORDS; ADU)
fwhm DOUBLE,
# FWHM assuming a gaussian core (SEXTRACTOR KEYWORDS; pixel)
ellipticity DOUBLE,
# ELLIPTICITY (SEXTRACTOR KEYWORDS)
class_star DOUBLE,
# S/G classifier output (SEXTRACTOR KEYWORDS)
sex_flag SMALLINT UNSIGNED,
# SExtractor extraction flags (SEXTRACTOR KEYWORDS)
mag_map DOUBLE,
# photometrically calibrated best mag.
# (derived and corrected by MAP; magnitude)
magerr_map DOUBLE,
# uncertainty of mag_map (magnitude)
ap_map DOUBLE,
# aperture diameter for mag_map (pixel)
refmag_map DOUBLE,
# magnitude with Max-AP via MAP (magnitude)
avg_delta_m DOUBLE,
# average of photometric calibration delta_m
std_delta_m DOUBLE,
# standard deviation of photometric calibration delta_m
skew_delta_m DOUBLE,
# skewness of photometric calibration delta_m
source_reliability DOUBLE,
photometry_reliability_n INT,
photometry_reliability_1 DOUBLE,
photometry_reliability_2 DOUBLE,
photometry_reliability DOUBLE
```

Source catalog table

5. Plan

– Continuous tests with the current data reduction process and stores for our pilot observation program until Sep. 2020.

– Expanding the current configuration of DBMS nodes in a public cloud from 4 nodes to 8 nodes for ClickHouse and MongoDB, respectively.



Current data reduction process and stores

```
{
  _id: ObjectID(),
  (given by mongoDB)
  object_id: KMTN083025.53-070822.5,
  ra: RA,
  (mean value for sources with source_reliability >= 19; degree)
  dec: DEC,
  (mean value for sources with source_reliability >= 19; degree)
  num_obs_lc: 111,
  (number of observation epochs given to the linking procedure)
  num_obs: 107,
  (number of observation epochs with reliable sources, i.e., source_reliability >= 19, used for the linking procedure)
  obs: [
    {source_id: 20190123032334p54, CTIO_09_34p73_32p34, filter: V, mjd: 653109.345572, ra: 34.567456, dec: -74.341096, mag_map: 16.564, magerr_map: 0.014, mag_auto: 16.780, magerr_auto: 0.023, sex_flag: 0, source_reliability: 65, photometry_reliability_n: 23, photometry_reliability_1: 0.003, photometry_reliability_2: 0.032, photometry_reliability: 0.931},
    {source_id: 20190123032423p26, CTIO_09_34p71_32p32, filter: V, mjd: 653109.985572, ra: 34.657456, dec: -74.341086, mag_map: 16.545, magerr_map: 0.0143, mag_auto: 16.791, magerr_auto: 0.021, sex_flag: 0, source_reliability: 86, photometry_reliability_n: 36, photometry_reliability_1: 0.0013, photometry_reliability_2: 0.0209, photometry_reliability: 0.71}
  ]
  process_datetime: date and time in UTC
}
```

Light curve example